# Gram-Schmidt Orthogonalization Process 

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## Definition

Let $V$ be an inner product space, $x, y \in V$. Let $A, B$ be subsets of $V$.

| $\langle x, y\rangle=0$ (we write $x \perp y$ ) | $x$ and $y$ are orthogonal <br> to each other |
| :--- | :--- |
| $x \perp y$ for every pair of distinct vectors <br> $x, y$ in $A$ | $A$ is orthogonal |
| $A$ is orthogonal and every vector in $A$ has <br> norm 1 | $A$ is orthonormal |
| every vector in $A$ is orthogonal to every <br> vector in $B$ | $A$ is orthogonal to $B$ |

## Definition

Let $S$ be a subspace of an inner product space. We say that $B$ is an orthogonal basis (resp. an orthonormal basis) of $S$ if $B$ is a basis of $S$ and $B$ is an orthonormal (resp. an orthonormal) set.

## Theorem

Every inner product space has an orthogonal (orthonormal) basis.

Proof. Start by selecting any nonzero vector $v_{1}$ in $V$. If $V$ contains a nonzero vector $v_{2}$ that is orthogonal to $v_{1}$, put it in the basis. If $V$ contains a nonzero vector $v_{3}$ that is orthogonal to $v_{1}$ and $v_{2}$, put it in the basis.

Proceed in this way. The chosen points $v_{1}, v_{2}, \ldots$ will be mutually orthogonal. The generated set is an orthogonal set, which is also a linearly independent. Thus, if $V$ is $n$ dimensional, the selection process certainly must stop after n steps.

If each vector $v_{i}$ is normalized, then the set is an orthonormal basis for $V$. Normalizing a vector $v$ means replacing $v$ by $v /\|v\|$. The norm of a vector is derived from the inner product : $\|x\|=\sqrt{\langle x, x\rangle}$.

A concrete realilzation of a process similar to the one just described is the Gram-Schmidt process. It operates in any finite dimensional inner product space and produces an orthonormal basis.

## Little information about Erhard Schmidt

Erhard Schmidt (1876-1959) was another important mathematician who serves as a professor of mathematics in several German universities. His advisor was David Hilbert (who formulated the theory of Hilbert spaces). Schmidt became an expert in the eigen functions that arise in the study of integral equations and partial differntial equations, and he was one of the


Erhard Schmidt first to make use of infinite dimensional vector spaces in his work.
He introduced the notation $\|$.$\| for the magnitude of a vector, \langle x, y\rangle$ for the inner product. He proved the Phythagorean theorem in abstract inner product spaces and many other results in this subject while it was in its infancy and new to almost all mathematicians. In a 1907 paper, Schmidt described what is now called the Gram-Schmidt process.

## Little information about Jorgen Pedersen Gram

Jorgen Pedersen Gram (1850-1916) published his first important mathematical paper while still a university student! Rather than teaching mathematics at a university he became a research mathematician employed by an insurance company. He published papers, gave lectures, and won awards for his mathematical research. At the age of 65, Gram was killed after being struck by a bicycle.


Jorgen Pedersen Gram

## Gram-Schmidt Algorithm

Suppose $\left\{v_{1}, v_{2}, \ldots, v_{n}\right\}$ is a basis of an inner product space $V$. For the frst step, we define $w_{1}$ to be the normalized version of $v_{1}$; that is, $w_{1}=v_{1} /\left\|v_{1}\right\|$.

For an inductive definition, suppose that we have constructed an orthonormal system $w_{1}, w_{2}, \ldots, w_{k-1}$ whose span is the same as span $\operatorname{span}\left\{v_{1}, v_{2}, \ldots, v_{k-1}\right\}$. To get $w_{k}$, subtract from $v_{k}$ its projection on the span of $\left\{w_{1}, w_{2}, \ldots, w_{k-1}\right\}$, and then normallize it.

The formula for this process is

$$
w_{k}=\frac{v_{k}-\sum_{j=1}^{k-1}\left\langle v_{k}, w_{j}\right\rangle w_{j}}{\left\|v_{k}-\sum_{j=1}^{k-1}\left\langle v_{k}, w_{j}\right\rangle w_{j}\right\|} \quad(k=2,3, \ldots, n)
$$

In this algorithm, the vectors are normalized as we go along. The new basis has the property that for each $k \leq n$,

$$
\operatorname{span}\left\{w_{1}, w_{2}, \ldots, w_{k}\right\}=\operatorname{span}\left\{v_{1}, v_{2}, \ldots, v_{k}\right\}
$$

## Unnormalized Gram-Schmidt Algorith

Theorem
Let $\left\{v_{1}, v_{2}, \ldots, v_{n}\right\}$ be a basis of a subspace $S$ of an inner product space V. Define $z_{1}, z_{2}, \ldots, z_{k}, \ldots, z_{n}$ inductively by :

$$
z_{k}=v_{k}-\sum_{j=1}^{k-1} \frac{\left\langle v_{k}, z_{j}\right\rangle}{\left\langle z_{j}, z_{j}\right\rangle} z_{j} \quad(k=1,2, \ldots, n) .
$$

Then $z_{1}, z_{2}, \ldots, z_{n}$ is an orthogonal basis of $S$.
An orthonormal basis of $V$ can be obtained by normalizing the $z_{i}$ 's.

Starting from any basis of an inner product space $V$, we can construct an orthonormal basis by the Gram-Schmidt process: Every finite-dimensional inner product space has an orthonormal basis.

## An Advantage in Unnormalized Gram-Schmidt Algorithm

The main difference between the algorithms for the $w_{k}$ (normalized) and $z_{k}$ (unnormalized) is that the vectors $w_{k}$ are normalized after each step, where the $z_{k}$ are not. Hence, they remain unnormalized! Avoiding the calculation of square root is another advantage.

For hand calculations, it is easier to construct an orthonormal basis by first constructing an orthogonal basis and then normalizing the vectors all at once at the end.

Next few slides are showing the Gram-Schmidt orthogonalization process in plane and space.

## Gram-Schmidt process in plane



The Gram-Schmidt process in plane

## Gram-Schmidt process in plane



## Gram-Schmidt process in plane



The Gram-Schmidt process in plane

## Gram-Schmidt process in plane



The Gram-Schmidt process in plane

## Gram-Schmidt process in plane



## Gram-Schmidt process in plane



The Gram-Schmidt process in plane

## Gram-Schmidt process in space



The Gram-Schmidt process in space

## Gram-Schmidt process in space



## The Gram̂-Schmidt process in space

## Gram-Schmidt process in space



The Gram-Schmidt process in space

## Gram-Schmidt process in space



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The Gram-Schmidt process in space

## Gram-Schmidt process in space



The Gram-Schmidt process in space

## Gram-Schmidt process in space

$$
\bar{w}-\frac{\vec{a}^{\prime} \cdot \vec{w}}{\left\|\vec{p}^{\prime}\right\|^{\prime}} a^{\prime}-\frac{\bar{v}^{\prime} \cdot \vec{w}}{\| \vec{p}^{\prime} \nabla^{\prime}}
$$

## The Gram-Schmidt process in space

## Generalized Gram-Schmidt Process

Let $x_{1}, x_{2}, \ldots, x_{s}$ be a given vectors in $V$, not necessarily basis.
(1) Step 1: Set $k=1$.
(2) Step 2: Compute $z_{k}=x_{k}-\sum_{j=1}^{k-1} \frac{\left\langle x_{k}, y_{j}\right\rangle}{y} j$.
(3) Step 3: Compute $y_{k}:=\frac{z_{k}}{\left\|z_{k}\right\|}$ or 0 according as $z_{k} \neq 0$ or $z_{k}=0$.
(4) Step 4: If $k<s$, increase $k$ by 1 and go to Step 2. Otherwise go to Step 5.
(6) Step 5: For $i=1,2, \ldots, s$, the set $B_{i}$ of all non-null vectors among $y_{1}, y_{2}, \ldots, y_{i}$ is an orthonormal basis of the span $S_{i}$ of $\left\{x_{1}, x_{2}, \cdots, x_{i}\right\}$.

If $x_{1}, x_{2}, \ldots, x_{\ell}$ form an orthonormal set then $y_{j}=x_{j}$ for $j=1,2, \ldots, \ell$.

## Theorem

Let $S$ be a subspace of a finite-dimensional inner product space V. Any orthonormal subset of $S$ can be extended to an orthonormal basis of $S$.

Proof. Let $A=\left\{x_{1}, x_{2}, \ldots, x_{\ell}\right\}$ be an orthonormal subset of $S$. Extend $A$ to a spanning set $\left\{x_{1}, x_{2}, \ldots, x_{\ell}, x_{\ell+1}, \ldots, x_{s}\right\}$ of $S$ by appending a basis. Applying the generallized Gram-Schmidt process to $\left\{x_{1}, x_{2}, \ldots, x_{s}\right\}$, get $\left\{y_{1}, y_{2}, \ldots, y_{s}\right\}$. Then the non-null vectors among $y_{1}, y_{2}, \ldots, y_{s}$ form an orthonormal basis of $S$ which contains $A=\left\{x_{1}, x_{2}, \ldots, x_{\ell}\right\}$.

We note that the orthonormal basis obtained by the Gram-Schmidt process from $x_{1}, x_{2}, \ldots, x_{\ell}$ may be quite different from that obtained from generallized Gram-Schmidt process (a rearrangement of $\left.x_{1}, x_{2}, \ldots, x_{\ell}\right)$.

## Exercises

(1) Consider $\mathbb{R}^{4}$ with the usual inner product. Extend

$$
\left\{\frac{1}{\sqrt{3}}(1,0,1,-1)^{T}, \frac{1}{\sqrt{7}}(-2,1,1,-1)^{T}\right\}
$$

to an orthonormal basis by the method of the preceding theorem.
(2) Consider the inner product $\langle x, y\rangle=y^{T} A x$ on $\mathbb{R}^{3}$ where

$$
A=\left(\begin{array}{ccc}
2 & 1 & -1 \\
1 & 1 & 0 \\
-1 & 0 & 3
\end{array}\right)
$$

Find an orthonormal basis $B$ of $S:=\left\{\left(x_{1}, x_{2}, x_{3}\right): x_{1}+x_{2}+x_{3}=0\right\}$ and then extend it to an orthonormal basis $\mathbb{C}$ of $\mathbb{R}^{3}$.

## $Q R$-decomposition

Let $A$ be an $n \times s$ matrix with rank $p$. Let $y_{1}, y_{2}, \ldots, y_{s}$ be the vectors obtained when generalized Gram-Schmidt process is applied to the columns of $A$. For each $k=1,2, \ldots, s$,

$$
z_{k}=A_{* k}-\sum_{j=1}^{k-1}\left\langle A_{* k}, y_{j}\right\rangle y_{j}=\left\|z_{k}\right\| y_{k}
$$

and, $y_{k}:=\frac{z_{k}}{\left\|z_{k}\right\|}$ or 0 according as $z_{k} \neq 0$ or $z_{k}=0$.
Hence $k$-th column of $A$ is a linear combination of $y_{1}, y_{2}, \ldots, y_{s}$. That is,

$$
A_{* k}=\left\langle A_{* k}, y_{1}\right\rangle y_{1}+\left\langle A_{* k}, y_{2}\right\rangle y_{2}+\cdots+\left\langle A_{* k}, y_{k-1}\right\rangle y_{k-1}+\left\|z_{k}\right\| y_{k} .
$$

## $Q R$-decomposition

$$
A=\left[\begin{array}{lll}
y_{1} & y_{2} & \cdots
\end{array} y_{s}[]\left[\begin{array}{ccccc}
\left\|z_{1}\right\| & \left\langle A_{* 2}, y_{1}\right\rangle & \left\langle A_{* 3}, y_{1}\right\rangle & \cdots & \left\langle A_{* s}, y_{1}\right\rangle \\
0 & \left\|z_{2}\right\| & \left\langle A_{* 3}, y_{2}\right\rangle & \cdots & \left\langle A_{* s}, y_{2}\right\rangle \\
0 & 0 & \left\|z_{3}\right\| & \cdots & \left\langle A_{* s}, y_{3}\right\rangle \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
0 & 0 & 0 & \cdots & \left\|z_{3}\right\|
\end{array}\right]\right.
$$

Let $U$ be the $s \times s$ upper triangular matrix $\left(u_{i k}\right)$ where

$$
u_{i k}=\left\{\begin{array}{cl}
\left\langle A_{* k}, y_{i}\right\rangle & \text { if } i<k \\
\left\|z_{k}\right\| & \text { if } i=k \\
0 & \text { otherwise }
\end{array}\right.
$$

Then $A=P U$.

Also if $Q$ is the submatrix of $P$ formed by the non-null columns (the columns of $Q$ form an orthonormal basis, $Q^{*} Q=I_{p}$ ) and $R$ the submatrix of $U$ formed by the corresponding rows, then $(Q, R)$ is a rank-factorization of $A$ and $Q^{*} Q=I_{p}$.

When $A$ is of full column rank $(Q, R)=(P, U)$ is known as a $Q R$-decomposition of $A$.

Uniqueness. $Q R$-factorization is unique if we insist that the diagonal elements of $R$ are real and positive, i.e., if $A$ is of full column rank, then there exist unique matrices $Q$ and $R$ such that $A=Q R, Q^{*} Q=I, R$ is upper triangular and $r_{i i}>0$ for all $i$.

## Exercises

(1) Let $x, y, u$ and $v$ belong to $\mathbb{R}^{n}$. Then show that

$$
\langle x+i y, u+i v\rangle:=u^{T} x+v^{T} y
$$

is an inner product on the vector space $\mathbb{C}^{n}$ over $\mathbb{R}$.
What is its connection with the canonical inner product on $\mathbb{C}^{n}$ ?
(2) Show that $\langle x, y\rangle=0$ for all $y$ iff $x=0$.

## Example on the space of random variables

Let $V$ be the vector space of all real-valued random variables with mean 0 and finite variance, defined on a fixed probability space. Let $F=\mathbb{R}$ and define $\langle x, y\rangle$ to be the covariance between $x$ and $y$.

- An orthogonal set is a set of pairwise uncorrelated random variables. They form an orthonormal set if, further, each of them has unit variance.
- Suppose $A=\left\{x_{1}, x_{2}, \ldots, x_{k}\right\}$ be an orthogonal set (not a basis) of non-null vectors in $V$. Then for any $x \in V$,

$$
z:=x-\sum_{j=1}^{k} \frac{\left\langle x, x_{j}\right\rangle}{\left\langle x_{j}, x_{j}\right\rangle} x_{j},
$$

the residual of $x$ with respect to $A$. The sum $\sum_{j=1}^{k} \frac{\left\langle x, x_{j}\right\rangle}{\left\langle x_{j}, x_{j}\right\rangle}$ is the linear regression of $x$ on $x_{1}, x_{2}, \ldots, x_{k}$.

## References

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- Ward Cheney and David Kincaid, "Linear Algebra - Theory and Applications", Jones \& Bartlett, 2010.

